

Industrial communication solutions for Windows

XWITNET Driver Manual

WIT-NET TRSII v4.7 Protocol Driver

Contents

XWITNET technical specifications	2
General information.....	2
Command list	2
Send Initialization Sequence	2
Request Access to device	2
Read System Identification.....	2
Read System Vars	3
Read System Trace.....	3
Read System Date	4
Read System Time.....	4
Write System Vars.....	5
Error messages	5
Supported devices.....	5

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XWITNET technical specifications

General information

The XWITNET driver implements a limited set of commands using the WIT-NET TRSII v4.7 protocol.

If you cannot communicate or if you are using RS-485 to connect to the device, you should set the RTS signal during the communication. This can be done by setting the RTSEnable argument when calling the read and write methods. If you still cannot communicate, check that your RS-485 cables are not inverted.

Command list

Send Initialization Sequence

Description of this command:

Sends an ESCAPE sequence to gain device's attention.

Methods used to run this command:

Digital Output

Number of points accepted by this command:

1

Meaning of the DriverP0 parameter:

0

Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Meaning of the DriverP6 parameter:

Initialization sequence. If left empty, the following sequence is assumed by default: 'W06'.

Important note:the indicated sequence is always sent after a 'ESC' character.

Request Access to device

Description of this command:

Requests access to the device by sending a password with the ACCESS command.

Methods used to run this command:

Analog Input

Number of points accepted by this command:

1

Meaning of the DriverP0 parameter:

5

Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Meaning of the DriverP6 parameter:

Password

Values that are returned:

Value in PointValue (0) = Status code

0 = Password is good

132 = Access denied

Read System Identification

Description of this command:

Reads information about the system identification, the system version and the system type.

System identification is returned as 15 separate chars, each as one PointValue containing the char ASCII code. If the identification string is shorter than 15 chars, remaining PointValues are padded with SPACES. The system version is returned as 3 separate chars. The system type is returned as 2 separate chars.

Possible types are:

10 = MONET II

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12 = BIMONET
20 = FORCE 100
24 = FORCE X
25 = FORCE BI-MODEM
26 = FORCE MINI
27 = FORCE PLUS
28 = FORCE ECO 2A = CLIP
29 = CLIP NANO
30 = MODEM RTC
31 = MODEM BUS LS
32 = MODEM RADIO
33 = MODEM LS It is up to the application to join each individual chars to create the resulting string.

Methods used to run this command:

Analog Input

Number of points accepted by this command:

20

Meaning of the DriverP0 parameter:

0

Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Values that are returned:

Value in PointValue (0-14) = Identification string (15 chars)

Value in PointValue (15-17) = Version string (3 chars)

Value in PointValue (18-19) = Type string (2 bytes)

Read System Vars

Description of this command:

Reads a consecutive group of variables, starting at a given VAR address (type and number).

Methods used to run this command:

Analog Input

Number of points accepted by this command:

1-250

Meaning of the DriverP0 parameter:

1

Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Meaning of the DriverP6 parameter:

Type and number of first variable. Possible types for FORCE are (x is the variable number): ETx = T.O.R. input STx = T.O.R. output EAx = Analog input SAx = Analog output VXx = Virtual variable VEx = Extension variable TB = Battery test TS = Sector test Possible types for CLIP are (y is the chart number and x is the variable number): Dly.x = T.O.R. input DOy.x = T.O.R. output AIx = Analog input AOx = Analog output Bx, Wx, Fx = Internal variables Br, Wr, Fr = Resource variables T Bat = Battery test T Sup = Sector test

Values that are returned:

Value in PointValue (0) = Value for first VAR requested

Value in PointValue (1) = Value for second VAR requested .

Value in PointValue (DriverNumPoints-1) = Value for last VAR requested

Read System Trace

Description of this command:

Reads a trace of up to 991 samples preceded by 9 values with information about the trace type, status, date and time.

Important note: Since this command brings a long reply, be sure to

set a long CommTimeout to permit the arrival of the full message.

Methods used to run this command:

Analog Input

Number of points accepted by this command:

9-1000

Meaning of the DriverP0 parameter:

2

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Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Meaning of the DriverP2 parameter:

Number of trace to read (1-80).

Meaning of the DriverP6 parameter:

Optional additional info to be included in the message sent. Examples:

- Use '20060131220030' to indicate that only samples registered after 22:00:30 of 31-01-2006 must be read.

- Use '53' to indicate that only the most recent 53 samples must be read.

Values that are returned:

Value in PointValue (0) = Type of trace:

1 = T.O.R. trace

2 = Analog trace

Value in PointValue (1) = Trace status

65 = Stopped

77 = Running

Value in PointValue (2) = Interval between samples in seconds

Value in PointValue (3) = Most recent sample day

Value in PointValue (4) = Most recent sample month

Value in PointValue (5) = Most recent sample year

Value in PointValue (6) = Most recent sample hour

Value in PointValue (7) = Most recent sample minutes

Value in PointValue (8) = Most recent sample seconds

Value in PointValue (9) = Value for first sample in trace

Value in PointValue (10) = Value for second sample in trace .

Value in PointValue (DriverNumPoints-1) = Value for last sample in trace

Read System Date

Description of this command:

Reads system current date.

Methods used to run this command:

Analog Input

Number of points accepted by this command:

3

Meaning of the DriverP0 parameter:

3

Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Values that are returned:

Value in PointValue (0) = System day

Value in PointValue (1) = System month

Value in PointValue (2) = System year

Read System Time

Description of this command:

Reads system current time.

Methods used to run this command:

Analog Input

Number of points accepted by this command:

3

Meaning of the DriverP0 parameter:

4

Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Values that are returned:

Value in PointValue (0) = System hour

Value in PointValue (1) = System minutes

Value in PointValue (2) = System seconds

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Write System Vars

Description of this command:

Writes a consecutive group of variables, starting at a given VAR address (type and number). Values are sent as floats with the selected number of decimals.

Methods used to run this command:

Analog Output

Number of points accepted by this command:

1-250

Meaning of the DriverP0 parameter:

1

Meaning of the DriverP1 parameter:

Encrypt/decrypt message (0=No, 1=Yes)

Meaning of the DriverP2 parameter:

Number of decimals (0-3)

Meaning of the DriverP6 parameter:

Type and number of first variable. Possible types for FORCE are (x is the variable number): ETx = T.O.R. input STx = T.O.R. output EAx = Analog input SAx = Analog output VXx = Virtual variable VEx = Extension variable TB = Battery test TS = Sector test Possible types for CLIP are (y is the chart number and x is the variable number): Dly.x = T.O.R. input DOy.x = T.O.R. output Alx = Analog input AOx = Analog output Bx, Wx, Fx = Internal variables Br, Wr, Fr = Resource variables TBat = Battery test TSup = Sector test

Values that are sent:

Value in PointValue (0) = Value for first VAR written

Value in PointValue (1) = Value for second VAR written .

Value in PointValue (DriverNumPoints-1) = Value for last VAR written

Error messages

The following list shows the possible error messages that can be returned by the driver during a failed communication in the 'Status' property.

[1005] DRIVER (Internal): Invalid driver stage
[1300] PROTOCOL (Timeout): No answer
[2122] CONFIG (NumValues): Invalid number of values (must be 3)
[2175] CONFIG (NumValues): Too many values (max=1)
[2203] CONFIG (NumValues): Too many values (max=250)
[2247] CONFIG (NumValues): Too many values requested (max=1000)
[2288] CONFIG (NumValues): Invalid number of values (must be 20)
[3001] CONFIG (P0): Invalid command
[3590] CONFIG (P1): Invalid mode
[4138] CONFIG (P2): Invalid trace number (1-80)
[4139] CONFIG (P2): Invalid number of decimals (0-3)
[6037] CONFIG (P6): Invalid variable
[6038] CONFIG (P6): Password not supplied

Supported devices

This driver can communicate with these devices, but is not necessarily limited to this list:

CLIP Systems
FORCE Systems
MONET Systems

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