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## XDANLOAD Driver Manual

*Emerson Daniel DanLoad 6000 Electronic Preset Protocol Driver*

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## XDANLOAD technical specifications

### General information

XDANLOAD driver allows you to connect to the Daniel Industries DanLoad 6000 Electronic Preset Unit using a modified version of the Modbus RTU protocol through special commands 41h and 42h.

The DanLoad 6000 has two communications 'channels' (ports) with the same address that can accept commands from automation systems. The address is set on the DUART board. Address zero should not be used since only "broadcast" messages would be processed and the DanLoad 6000 would not respond to any query.

If two automation systems are connected to the DanLoad 6000, one of them is typically responsible for 'authorization', and the other one for 'monitoring' (unless the two automation systems engage in some form of handshaking--possibly via the DanLoad 6000's status bits). The DanLoad 6000 receives queries on both communications channels (possibly simultaneously) and (if the query is not a retry) queues them to a single internal process which is responsible for building the response. Thus, queries are handled on a "first come, first served" basis, but an automation system never has to wait, i.e. worst case, for longer than it takes to respond to a single query on the other channel since it will always have the next place in the queue. When a response has been built, it is handed back to the appropriate channel process, i.e. the one for which the query was received, in order to be transmitted to the automation system.

For DanLoad 6000 v5.30 and above, program code 662 must be used to configure the unit's communications address; the DUART's address switch is no longer used.

Communications are full-duplex operating as master/slave.

The maximum number of slaves on a common line (multidrop) is 32. In practice, due to cable lengths and data rates a smaller number of slaves may be necessary.

The DanLoad 6000 operates as an addressable slave station, and 'speaks only when spoken to'; this is a necessary consequence of RS-485 multidrop communications, which requires that a slave station reply only to a message directed to it.

The DanLoad 6000 does not respond to a message that is 'incorrectly framed', i.e. not its address, an unused function code or an incorrect error check.

The DanLoad 6000 does not respond to a message that is 'incomplete', i.e. fewer or more characters than expected.

The DanLoad 6000 ignores (throws away) any characters that are transmitted to it by the automation system while it is processing a previous command from the automation system.

The DanLoad 6000 is not ready to receive characters until a few milliseconds after it has completed a transmission. The automation system should delay 50 milliseconds between receiving the last character of a message from a DanLoad 6000 and transmitting the first character of a message to the same DanLoad 6000. If necessary, this delay can be configured with the CommT3Delay property.

This driver can only be used as the master in the communication network and it does not support exception messages. The device should behave as a slave in your RS-232/485 network.

This driver supports serial-over-ethernet.

#### Important note:

If you communicate using a serial port, this driver can detect a DanLoad 6000 timeout condition and automatically send a Start Communications attempt followed by a command retry before abandoning the communication and throwing a communication error.

If you are using serial-over-ip with an ip-to-serial converter, the driver will not send the Start Communications command automatically and thus it should be specifically called by your application when a communication error is detected.

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## Command list

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### Start Communications

**Description of this command:**

When the DanLoad 6000 is powered-up/reset, exits program mode or has detected an automation system communications failure, communications can be started with this command.

The DanLoad 6000 will not respond to any command from the automation system until communications have been started.

If communications are already started when this command is received then the communications link is reinitialized but operations at the DanLoad 6000 are unaffected.

When a communications failure occurs on a communications channel then communications on that channel can be started using this command.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

7+2\*Max. configured number of components

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

21h (33 dec)

**Meaning of the DriverP2 parameter:**

Meter Number (1-4)

**Values that are returned:**

Value in PointValue (0) = Configured number of meters

Value in PointValue (1) = Configured number of components

Value in PointValue (2) = Configured number of valves

Value in PointValue (3) = Configured number of factors/component

Value in PointValue (4) = Configured number of recipes

Value in PointValue (5) = Configured number of additives

Value in PointValue (6) = Temp units (0=Celsius, 1=Fahrenheit)

- for i=0 to Configured number of components-1

Value in PointValue (7+2\*i) = Temperature correction option for component i

Value in PointValue (8+2\*i) = Pressure correction option for component i

- next i

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- None

**Important note:**

The driver will stop assigning PointValues when it reaches the configured DriverNumPoints.

Remaining PointValues will be filled with a value of -1.

### Request Meter Values

**Description of this command:**

This commands causes the DanLoad 6000 to respond with the current values of various data.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

16+Max. number of factors or flow rates

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

19h (25 dec)

**Meaning of the DriverP2 parameter:**

Meter number (1-4)

**Values that are returned:**

Value in PointValue (0) = Meter number

Value in PointValue (1) = Gross totalizer rolls 99999999 to 0

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Value in PointValue (2) = Net volume or mass/weight totalizer rolls 999999999 to Q  
Value in PointValue (3) = Batch gross whole units  
Value in PointValue (4) = Batch net volume or mass/weight whole units  
Value in PointValue (5) = Average over one second flow rate  
Value in PointValue (6) = Average batch flow rate. Not implemented  
Value in PointValue (7) = Maximum average over one second flow rate  
Value in PointValue (8) = Current meter factor  
Value in PointValue (9) = Current pulse count rolls 65535 to 0  
Value in PointValue (10) = Number of factors or flow rates  
- for i=0 to Number of factors or flow rates-1  
Value in PointValue (11+i) = Number of pulses at flow rate  
- next i  
Value in PointValue (11+[Number of pulses at flow rate]+0) = Gross unauthorized flow l0ths since start of last batch  
Value in PointValue (11+[Number of pulses at flow rate]+1) = Net volume or mass/weight unauthorized flow l0ths since start of last batch. Net = gross for unauth. flow volume  
Value in PointValue (11+[Number of pulses at flow rate]+2) = Current temperature  
Value in PointValue (11+[Number of pulses at flow rate]+3) = Current density  
Value in PointValue (11+[Number of pulses at flow rate]+4) = Current pressure

#### Status flags immediately set:

- None

#### Status flags immediately cleared:

- None

#### Reported exceptions:

- 41h Invalid meter number

#### Important note:

The driver will stop assigning PointValues when it reaches the configured DriverNumPoints. Remaining PointValues will be filled with a value of -1.

## Authorize Transaction

#### Description of this command:

A transaction for recipe 'recipenumber', side 'side' and additives determined by 'addsel' and 'addselmthd' is authorized but started.

The automation system indicates on which side (1 or 2) loading authorized to take place. The value 1 should be used for nonswing-arm applications.

'addsel' is the additive selection which determines which additive ratio outputs are cycled during a batch.

*The additive selection methods (addselmthd) are:*

0 = Additive selection per addsel in the Authorize Transaction command, i.e. selected by automation system.

1 = Additive selection per DanLoad 6000's configured additive selection method (program code 136).

A fault in the standard DanLoad 6000 v5.40 (and below) firmware prevents the automation system from selecting the additives through communications if the configured additive selection method is 'Inputs'.

If additives are enabled via external (to the DanLoad 6000) contacts that complete electrical circuits between the DanLoad 6000's additive ratio outputs and the additive injectors, the automation system should select all (six) additives by setting addselmthd to 0 and addsel to 3Fh (00111111 binary), though fewer (than six) additives may be configured on the DanLoad 6000 (program code 135).

An alternative is for the automation system to set bits in addsel based on the configured number of additives in the DanLoad 6000's response to the Start Communications command.

Bear in mind that it is possible for each DanLoad to have a different configured number of additives. The automation system can include up to five data items (each in the range 0 to 99999999) for the DanLoad 6000 to store in transaction storage memory, e.g. previously entered order number or driver number. In the manual operating mode, the DanLoad 6000 can prompt the operator for these data items and store them in transaction storage memory.

The DanLoad 6000 indicates the transaction sequence number (transeqnum) that will be used if a transaction is later started by starting the first batch on the transaction.

The transaction sequence number rolls from 9999 to 0.

The DanLoad 6000 displays the loading display (if it is not already displayed) and displays 'Please wait'. (The Authorized Transaction command is the means by which the automation system

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causes the loading screen to be displayed.) The 'large number' preset volume on the loading display is cleared (if it is present). The batch loaded, preset and remaining volumes and the transaction volume are zeroed. Status flag 12h (Transaction authorized) will be set subsequently.

## Methods used to run this command:

Analog Input

## Number of points accepted by this command:

1

## Meaning of the DriverP0 parameter:

Device number (1-255)

## Meaning of the DriverP1 parameter:

06h (6 dec)

## Meaning of the DriverP2 parameter:

Recipe number (1-30)

## Meaning of the DriverP3 parameter:

Additive selection method (0-1)

## Meaning of the DriverP4 parameter:

Additive selection bit map (see note below)

## Meaning of the DriverP5 parameter:

Swing-arm side (0-2)

## Meaning of the DriverP6 parameter:

Number of data prompts (0-5)

## Meaning of the DriverP7 parameter:

Comma-separated list of data prompts (xxxxx,xxxxx,xxxxx,...)

## Values that are returned:

Value in PointValue (0) = Prospective transaction sequence number

## Status flags immediately set:

- 14h Keypad and display locked out

## Status flags immediately cleared:

- 04h Recipe selected
- 05h Additive selected
- 0Ch Transaction ended
- 13h Transaction end requested

## Reported exceptions:

- 01h Passcode entry in progress
- 0Ah Primary alarm active
- 0Ch Transaction authorized
- 10h Additive not available
- 15h Operating mode is manual (low priority, may not be seen!)
- 24h Keypad and display locked out
- 40h Invalid recipe number
- 48h Invalid number of data prompts
- 49h Invalid swing-arm side (0-2)
- 4Eh Invalid additive selection method

## ADDITIVE SELECTION CODES:

The additive selection code is a binary representation of selection byte.

- Bit 0 = Additive 1 on/off
- Bit 1 = Additive 2 on/off
- Bit 2 = Additive 3 on/off
- Bit 3 = Additive 4 on/off
- Bit 4 = Additive 5 on/off
- Bit 5 = Additive 6 on/off
- Bit 6 = Not used, always 0
- Bit 7 = Not used, always 0

## *Code (hex) Interpretation:*

Additive #		1	2	3	4	5	6
- ##		1	2	3	4	5	6
- 00	Off	Off	Off	Off	Off	Off	Off
- 01	On	Off	Off	Off	Off	Off	Off
- 02	Off	On	Off	Off	Off	Off	Off
- 03	On	On	Off	Off	Off	Off	Off

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- 04 Off Off On Off Off Off
- 05 On Off On Off Off Off
- 06 Off On On Off Off Off
- 07 On On On Off Off Off
- 08 Off Off Off On Off Off
- 09 On Off Off On Off Off
- 0A Off On Off On Off Off
- 0B On On Off On Off Off
- 0C Off Off On On Off Off
- 0D On Off On On Off Off
- 0E Off On On On Off Off
- 0F On On On On Off Off
- ...
- 3E Off On On On On On
- 3F On On On On On On

## Configure Recipe

### Description of this command:

This command is a short-cut for configuring recipes (instead of setting the individual program code values).

In the case of an in-line blender unit type there are some other considerations. The low/high proportion flags should be configured carefully; it is possible that a particular component is high proportion (flag = 0) for some recipes and low proportion (flag = 1) for different recipes on the same DanLoad 6000. This is a function of the size of the meter (and thus the usable range of flow rates) through which the component flows. The overall recipe flow rates (program codes 776, 777, etc.) may need to be modified if component percentages are modified via communications. (The component stop rates and calibrated meter factor flow rates should not normally be modified dynamically.).

The configured number of recipes (program code 480) is not automatically increased or decreased by the Configure Recipe command.

### Methods used to run this command:

Analog Output

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

27h (39 dec)

### Meaning of the DriverP2 parameter:

Recipe number (1-30)

### Meaning of the DriverP3 parameter:

Configured number of components

### Meaning of the DriverP4 parameter:

Not used

### Meaning of the DriverP5 parameter:

Not used

### Meaning of the DriverP6 parameter:

Recipe name (max. length is 16 chars)

### Meaning of the DriverP7 parameter:

Comma-separated list of component percentages in hundredths (xx,xx,xx,...)

### Meaning of the DriverP8 parameter:

Comma-separated list of component sequence or low/high proportion (xx,xx,xx,...)

### Values that are sent:

Value in PointValue (0) = Ignored. Can be any value.

### Status flags immediately set:

- 08h Program code value(s) changed

### Status flags immediately cleared:

- None

### Reported exceptions:

- OAh Primary alarm active
- OCh Transaction authorized
- 15h Operating mode is manual (low priority, may not be seen!)

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- 40h Invalid recipe number
- 47h Invalid number of components

## Important note:

This command does not use the values assigned to the PointValue properties, which means that any value there will be ignored.

## Authorize Batch

### Description of this command:

The preset volume is 'set' in the DanLoad 6000 so that it can be loaded. The DanLoad 6000 displays 'Press START when ready or STOP to cancel'. The 'START' and 'STOP' keys are enabled. The operator has timeout seconds to press the 'START' key or the batch is automatically aborted.

The preset volume must not be greater than the configured maximum preset volume (program code 078) and must not be less than the configured minimum preset volume (program code 079). The preset volume is in the units of volume implied by the component's nominal K-factors and meter factors.

If the use\_gord flag is set the configured backup density or gravity is replaced by the value in the message. The units of gravity or density should be the same as those in use by the DanLoad 6000 (program code 432, etc.).

If the use temp flag is set the configured backup temperature is replaced by the temp in the message. The units of temperature should be the same as those in use by the DanLoad 6000 (program codes 427, 432, etc.).

The DanLoad 6000 indicates the (prospective) batch sequence number (batchseqnum) that will be used if a batch is started. The batch sequence number rolls from 9999 to 0.

Status flag 11 h (Batch authorized) will be set.

Valid modes: Automatic.

### Methods used to run this command:

Analog Input

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

0Ah (10 dec)

### Meaning of the DriverP2 parameter:

Preset volume

### Meaning of the DriverP3 parameter:

Configured number of components (0-30)

### Meaning of the DriverP4 parameter:

Time-out seconds (0=No time-out, <0=Use configured time-out)

### Meaning of the DriverP5 parameter:

Not used

### Meaning of the DriverP6 parameter:

Comma-separated list of backup gravities or densities (gord) and temperatures (temp) for each component. Values can be empty. Example:

(gord1,temp1,gord2,temp2,,temp3,gord4,,gord5,temp5,...)

### Values that are returned:

Value in PointValue (0) = Prospective batch sequence number

### Status flags immediately set:

- 14h Keypad and display locked out

### Status flags immediately cleared:

- 03h Operation timed out
- 06h Preset volume entered
- 0Dh Batch ended
- 0Eh Batch aborted (not started)

### Reported exceptions:

- 0lh Passcode entry in progress
- 04h Program code value is Weights and Measures (backup density/gravity or temperature)
- 0Ah Primary alarm active
- 0Bh Batch authorized
- 11h Program code value is read only
- 15h Operating mode is manual (low priority, may not be seen!)

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- 22h No transaction authorized
- 24h Keypad and display locked out
- 45h Invalid program code value (backup density/gravity or temperature)
- 47h Invalid number of components
- 4Fh Invalid preset volume

## Start Batch

### Description of this command:

A batch must previously have been authorized using the Authorize Batch command. The DanLoad 6000 starts delivery of the batch. (This is the same as pressing the 'START' key at the appropriate time.).

This command is used to start a batch that has been authorized but is not yet in progress or to restart a batch in progress that has been stopped.

This is used for 'remote control' of the DanLoad 6000, where there cannot be an operator in proximity of the DanLoad 6000. In these circumstances the DanLoad 6000 may be controlled entirely from the automation system, and the DanLoad 6000 may not even be fitted with a display or keypad. In this way, barges or railcars can be loaded from a control room.

Valid modes: Automatic.

### Methods used to run this command:

Analog Input

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

0Eh (14 dec)

### Values that are returned:

Value in PointValue (0) = Batch sequence number

### Status flags immediately set:

- 0Ah Batch in progress

### Status flags immediately cleared:

- 15h Batch stopped (resumable)

### Reported exceptions:

- 0Ah Primary alarm active
- 14h No batch authorized
- 15h Operating mode is manual (low priority, may not be seen!)

## Stop Batch

### Description of this command:

The batch in progress is stopped. This simulates the 'STOP' key being pressed. The manner in which the batch is stopped is determined by the programmed 'STOP' key action.

The DanLoad 6000 sets a flag to indicate that the batch has stopped (and is restartable) or that the batch has ended. If the batch has stopped (and is restartable) the DanLoad 6000 displays 'Press START when ready or STOP to cancel'.

The DanLoad 6000 displays 'Please wait'.

Valid modes: Automatic.

### Methods used to run this command:

Analog Input

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

0Fh (15 dec)

### Values that are returned:

Value in PointValue (0) = Batch sequence number

### Status flags immediately set:

- None

### Status flags immediately cleared:

- None

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## Reported exceptions:

- 06h No batch in progress
- 15h Operating mode is manual (low priority, may not be seen!)

## End Batch

### Description of this command:

If there is a batch in progress and stopped it is ended. The DanLoad 6000 sets a flag to indicate that the batch has ended (which implies it is non-restartable). This is a signal for the automation system to request batch data. The DanLoad 6000 stores batch data and transaction data in 'transaction storage memory'. The DanLoad 6000 displays 'Please wait'.

Status flag OAh (Batch in progress) is cleared, ODh (Batch ended) is set and 15h (Batch stopped) is cleared.

This is not the same as the Stop Batch command, which simulates the 'STOP' key being pressed, and therefore potentially allows the batch to be restarted.

Under normal circumstances a batch ends (by itself) when the preset volume has been delivered. Use the Time-Out Operation command to abort a batch that has been authorized but not yet started.

Valid modes: Automatic.

### Methods used to run this command:

Analog Input

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

0Dh (13 dec)

### Values that are returned:

Value in PointValue (0) = Batch sequence number

### Status flags immediately set:

- None

### Status flags immediately cleared:

- None

### Reported exceptions:

- 06h No batch in progress
- 15h Operating mode is manual (low priority, may not be seen!)

## Batch Data By Component

### Description of this command:

The DanLoad 6000 sets a flag to indicate that a batch has ended and cannot be restarted. The automation system can request data for the batch.

The DanLoad 6000's response include the configured number of components numcomps (program code 065) and the configured number of additives numadds (program code 135).

A component's batch net equals its batch gross and its temperature and density are 'not defined', i.e. they are garbage, if a C method (temperature option) is not specified for the component.

(Program code 432, etc.).

Valid modes: Automatic.

### Methods used to run this command:

Analog Input

### Number of points accepted by this command:

7+2\*Max. configured number of components

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

10h (16 dec)

### Values that are returned:

Value in PointValue (0) = Batch sequence number

Value in PointValue (1) = Transaction sequence number

Value in PointValue (2) = Recipe number

Value in PointValue (3) = Swing-arm side (0-2)

Value in PointValue (4) = Batch start year

Value in PointValue (5) = Batch start month

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Value in PointValue (6) = Batch start day  
Value in PointValue (7) = Batch start hours  
Value in PointValue (8) = Batch start mins  
Value in PointValue (9) = Batch start secs  
Value in PointValue (10) = Batch end year  
Value in PointValue (11) = Batch end month  
Value in PointValue (12) = Batch end day  
Value in PointValue (13) = Batch end hours  
Value in PointValue (14) = Batch end mins  
Value in PointValue (15) = Batch end secs  
Value in PointValue (16) = Configured number of meters  
Value in PointValue (17) = Configured number of components  
Value in PointValue (18) = Number of additives  
Value in PointValue (19) = Number of data prompts (0-5)  
- for i=0 to [Number of meters]-1  
Value in PointValue (20+4\*i+0) = Gross meter totalizer at start of batch  
Value in PointValue (20+4\*i+1) = Net volume or mass/weight meter totalizer at start of batch  
Value in PointValue (20+4\*i+2) = Gross meter totalizer at start of batch  
Value in PointValue (20+4\*i+3) = Net volume or mass/weight meter totalizer at end of batch  
- next i  
- for i=0 to Number of additives-1  
Value in PointValue (20+4\*[Number of meters]+6\*i+0) = Gross batch whole units  
Value in PointValue (20+4\*[Number of meters]+6\*i+1) = Net volume or mass/weight batch whole units  
Value in PointValue (20+4\*[Number of meters]+6\*i+2) = Average temperature  
Value in PointValue (20+4\*[Number of meters]+6\*i+3) = Average density  
Value in PointValue (20+4\*[Number of meters]+6\*i+4) = Average pressure XXXX.XX  
Value in PointValue (20+4\*[Number of meters]+6\*i+5) = Actual in batch x100, e.g. 6003 for 60.03  
- next i  
- for i=0 to Number of components-1  
Value in PointValue (20+4\*[Number of meters]+6\*[Number of additives]+i) = Additive batch volume. Implied scaling depends on additive units  
- next i  
- for i=0 to Number of data prompts-1  
Value in PointValue (20+4\*[Number of meters]+6\*[Number of additives]+[Number of data prompts]+i) = Data items  
- next i

#### Status flags immediately set:

- None

#### Status flags immediately cleared:

- None

#### Reported exceptions:

- 15h Operating mode is manual (low priority, may not be seen!)
- 26h No batch ended

#### Important note:

The driver will stop assigning PointValues when it reaches the configured DriverNumPoints. Remaining PointValues will be filled with a value of -1.

## End Transaction

#### Description of this command:

The side should be the swing-arm side on which the transaction was authorized. If there is a transaction in progress the DanLoad 6000 performs 'end of transaction' processing. If a transaction is authorized but there is no transaction in progress the DanLoad 6000 does not perform 'end of transaction' processing but simply deauthorizes the transaction.

The DanLoad 6000 stores further transaction data, i.e. date, time, gross volume, net volume or mass/weight, average temperature, etc. The DanLoad 6000 responds with the transaction sequence number of the transaction that will be ended.

Status flag 09h (Transaction in progress) is cleared subsequently, OCh (Transaction ended) is set subsequently and 1 2h (Transaction authorized) is cleared subsequently. The DanLoad 6000 displays 'Please wait'.

In the manual operating mode a transaction is ended by pressing the 'STOP' key when there is a transaction in progress and a batch is stopped or ended or there is no batch in progress. In

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automatic operating mode pressing the 'STOP' key when there is a transaction in progress and a batch is stopped or ended or there is no batch in progress does not end the transaction. Instead, the DanLoad 6000 sets a flag indicating that a request has been made to end the transaction, to which the automation system can send an End Transaction command to one or more DanLoad 6000's (or simply clear or ignore the flag).

Valid modes: Automatic.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

1

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

07h (7 dec)

**Meaning of the DriverP2 parameter:**

Swing-arm side (0-2)

**Values that are returned:**

Value in PointValue (0) = Prospective transaction sequence number

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 08h Batch in progress

- 15h Operating mode is manual (low priority, may not be seen!)

- 22h No transaction authorized

- 49h Invalid swing-arm side

## Transaction Data by Component

**Description of this command:**

When a transaction ends the DanLoad 6000 sets a flag indicating that the transaction has ended. This command is used to request transaction data from the DanLoad 6000 when a transaction ends.

In manual, a transaction is ended by pressing the 'STOP' key when there is a transaction in progress and no batch in progress. In automatic, a transaction is ended by the automation system via the End Transaction command.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

1

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

1Fh (31 dec)

**Meaning of the DriverP2 parameter:**

Transaction sequence number

**Values that are returned:**

Value in PointValue (0) = Transaction sequence number

Value in PointValue (1) = Recipe number

Value in PointValue (2) = Swing-arm side (0-2)

Value in PointValue (3) = Transaction gross volume

Value in PointValue (4) = Transaction net volume or mass/weight

Value in PointValue (5) = Transaction start year

Value in PointValue (6) = Transaction start month

Value in PointValue (7) = Transaction start day

Value in PointValue (8) = Transaction start hours

Value in PointValue (9) = Transaction start mins

Value in PointValue (10) = Transaction start secs

Value in PointValue (11) = Transaction end year

Value in PointValue (12) = Transaction end month

Value in PointValue (13) = Transaction end day

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Value in PointValue (14) = Transaction end hours  
Value in PointValue (15) = Transaction end mins  
Value in PointValue (16) = Transaction end secs  
Value in PointValue (17) = Configured number of meters  
Value in PointValue (18) = Number of data prompts (0-5)  
- for i=0 to [Number of meters]-1  
Value in PointValue (19+4\*i+0) = Gross meter totalizer at start of batch  
Value in PointValue (19+4\*i+1) = Net volume or mass/weight meter totalizer at start of batch  
Value in PointValue (19+4\*i+2) = Gross meter totalizer at end of batch  
Value in PointValue (19+4\*i+3) = Net volume or mass/weight totalizer at end of batch  
- next i  
- for i=0 to [Number of data prompts]-1  
Value in PointValue (19+4\*[Number of meters]+i) = Data items entered by operator in manual or downloaded by automation system in automatic  
- next i

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 02h No transaction ended  
- 43h Invalid transaction sequence number

## Request Status

**Description of this command:**

'status' is a binary representation of the DanLoad 6000's 32 status flags.

'safety' is a binary representation of the current logical state ('open' or 'closed') of the DanLoad 6000's eight general-purpose safety circuits (program codes 345 through 352). The least significant bit is safety circuit 1, etc. Safety circuits that are not configured on the DanLoad 6000 are indicated to be 'open', i.e. the corresponding bit is 0.

'alarm\_byte\_0' through 'alarm\_byte\_9' indicate active (raised and not reset) primary alarms. The automation system can maintain a copy of the 'alarm bytes' so that it can determine when primary alarms are raised and cleared for logging purposes.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

1-124

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

12h (18 dec)

**Values that are returned:**

Value in PointValue (0) = Status flag 0: 00hB Operating mode is manual

Value in PointValue (1) = Status flag 1: 01hB Primary alarm

Value in PointValue (2) = Status flag 2: 02h\* Passcode entry in progress

Value in PointValue (3) = Status flag 3: 03h\*#a Operation timed out

Value in PointValue (4) = Status flag 4: 04h\*#a Recipe selected

Value in PointValue (5) = Status flag 5: 05h\*#a Additives selected, i.e. additive selection complete

Value in PointValue (6) = Status flag 6: 06h\*#a Preset volume entered

Value in PointValue (7) = Status flag 7: 07h\*#a Keypad data available

Value in PointValue (8) = Status flag 8: 08ha Program code value(s) changed

Value in PointValue (9) = Status flag 9: 09h\* Transaction in progress

Value in PointValue (10) = Status flag 10: 0Ah\*B Batch in progress (doesn't necessarily imply delivery)

Value in PointValue (11) = Status flag 11: 0Bh\*a Key pressed (DanLoad 6000 v5.1 1 and above)

Value in PointValue (12) = Status flag 12: 0Cha Transaction ended

Value in PointValue (13) = Status flag 13: 0Dha Batch ended

Value in PointValue (14) = Status flag 14: 0Eh\*a Batch aborted (not started)

Value in PointValue (15) = Status flag 15: 0Fh\*a Intermediate level input alarm stopped batch (v5.50)

Value in PointValue (16) = Status flag 16: IOh RESERVED

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Value in PointValue (17) = Status flag 17: 11h Batch authorized  
Value in PointValue (18) = Status flag 18: 12h Transaction authorized  
Value in PointValue (19) = Status flag 19: 13ha Transaction end requested ("STOP" key in auto)  
Value in PointValue (20) = Status flag 20: 14h Keypad and display locked out to automation system  
Value in PointValue (21) = Status flag 21: 15h Batch stopped (resumable)  
Value in PointValue (22) = Status flag 22: 16ha Program mode  
Value in PointValue (23) = Status flag 23: 17h\* Flowing, i.e. batch in progress and not stopped  
Value in PointValue (24) = Status flag 24: 18h RESERVED  
Value in PointValue (25) = Status flag 25: 19h RESERVED  
Value in PointValue (26) = Status flag 26: 1Ah RESERVED  
Value in PointValue (27) = Status flag 27: 1Bh RESERVED  
Value in PointValue (28) = Status flag 28: 1Ch RESERVED  
Value in PointValue (29) = Status flag 29: 1Dh RESERVED  
Value in PointValue (30) = Status flag 30: 1Eh RESERVED  
Value in PointValue (31) = Status flag 31: 1Fh RESERVED  
Value in PointValue (32) = Swing-arm side (0-2)  
Value in PointValue (33) = Batch gross volume whole units. \*7  
Value in PointValue (34) = Batch net volume or mass/weight whole units. \*7  
Value in PointValue (35) = Safety circuit 1 status  
Value in PointValue (36) = Safety circuit 2 status  
Value in PointValue (37) = Safety circuit 3 status  
Value in PointValue (38) = Safety circuit 4 status  
Value in PointValue (39) = Safety circuit 5 status  
Value in PointValue (40) = Safety circuit 6 status  
Value in PointValue (41) = Safety circuit 7 status  
Value in PointValue (42) = Safety circuit 8 status  
Value in PointValue (43) = Alarm code of oldest active primary alarm  
Value in PointValue (44) = Alarm flag 0: Primary display failure  
Value in PointValue (45) = Alarm flag 1: Secondary display failure  
Value in PointValue (46) = Alarm flag 2: Comms failure channel A  
Value in PointValue (47) = Alarm flag 3: Comms failure channel B  
Value in PointValue (48) = Alarm flag 4: Unable to maintain blend  
Value in PointValue (49) = Alarm flag 5: Flow rate too low meter 1  
Value in PointValue (50) = Alarm flag 6: Flow rate too low meter 2  
Value in PointValue (51) = Alarm flag 7: Flow rate too low meter 3  
Value in PointValue (52) = Alarm flag 8: Flow rate too low meter 4  
Value in PointValue (53) = Alarm flag 9: Flow rate too high meter 1  
Value in PointValue (54) = Alarm flag 10: Flow rate too high meter 2  
Value in PointValue (55) = Alarm flag 11: Flow rate too high meter 3  
Value in PointValue (56) = Alarm flag 12: Flow rate too high meter 4  
Value in PointValue (57) = Alarm flag 13: Valve closed early meter 1  
Value in PointValue (58) = Alarm flag 14: Valve closed early meter 2  
Value in PointValue (59) = Alarm flag 15: Valve closed early meter 3  
Value in PointValue (60) = Alarm flag 16: Valve closed early meter 4  
Value in PointValue (61) = Alarm flag 17: Time-out - no flow detected meter 1  
Value in PointValue (62) = Alarm flag 18: Time-out - no flow detected meter 2  
Value in PointValue (63) = Alarm flag 19: Time-out - no flow detected meter 3  
Value in PointValue (64) = Alarm flag 20: Time-out - no flow detected meter 4  
Value in PointValue (65) = Alarm flag 21: Unauthorized flow exceeds limit meter 1  
Value in PointValue (66) = Alarm flag 22: Unauthorized flow exceeds limit meter 2  
Value in PointValue (67) = Alarm flag 23: Unauthorized flow exceeds limit meter 3  
Value in PointValue (68) = Alarm flag 24: Unauthorized flow exceeds limit meter 4  
Value in PointValue (69) = Alarm flag 25: Pulse security error meter 1  
Value in PointValue (70) = Alarm flag 26: Pulse security error meter 2  
Value in PointValue (71) = Alarm flag 27: Pulse security error meter 3  
Value in PointValue (72) = Alarm flag 28: Pulse security error meter 4  
Value in PointValue (73) = Alarm flag 29: Temperature failure meter 1  
Value in PointValue (74) = Alarm flag 30: Temperature failure meter 2  
Value in PointValue (75) = Alarm flag 31: Temperature failure meter 3  
Value in PointValue (76) = Alarm flag 32: Temperature failure meter 4  
Value in PointValue (77) = Alarm flag 33: Pressure failure meter 1

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Value in PointValue (78) = Alarm flag 34: Pressure failure meter 2  
Value in PointValue (79) = Alarm flag 35: Pressure failure meter 3  
Value in PointValue (80) = Alarm flag 36: Pressure failure meter 4  
Value in PointValue (81) = Alarm flag 37: Unable to close valve meter 1  
Value in PointValue (82) = Alarm flag 38: Unable to close valve meter 2  
Value in PointValue (83) = Alarm flag 39: Unable to close valve meter 3  
Value in PointValue (84) = Alarm flag 40: Unable to close valve meter 4  
Value in PointValue (85) = Alarm flag 41: Density failure component 1  
Value in PointValue (86) = Alarm flag 42: Density failure component 2  
Value in PointValue (87) = Alarm flag 43: Density failure component 3  
Value in PointValue (88) = Alarm flag 44: Density failure component 4  
Value in PointValue (89) = Alarm flag 45: Component 1 block valve not closed  
Value in PointValue (90) = Alarm flag 46: Component 2 block valve not closed  
Value in PointValue (91) = Alarm flag 47: Component 3 block valve not closed  
Value in PointValue (92) = Alarm flag 48: Component 4 block valve not closed  
Value in PointValue (93) = Alarm flag 49: Additive 1 failure  
Value in PointValue (94) = Alarm flag 50: Additive 2 failure  
Value in PointValue (95) = Alarm flag 51: Additive 3 failure  
Value in PointValue (96) = Alarm flag 52: Additive 4 failure  
Value in PointValue (97) = Alarm flag 53: Additive 5 failure  
Value in PointValue (98) = Alarm flag 54: Additive 6 failure  
Value in PointValue (99) = Alarm flag 55: Safety circuit 1  
Value in PointValue (100) = Alarm flag 56: Safety circuit 2  
Value in PointValue (101) = Alarm flag 57: Safety circuit 3  
Value in PointValue (102) = Alarm flag 58: Safety circuit 4  
Value in PointValue (103) = Alarm flag 49: Safety circuit 5  
Value in PointValue (104) = Alarm flag 60: Safety circuit 6  
Value in PointValue (105) = Alarm flag 61: Safety circuit 7  
Value in PointValue (106) = Alarm flag 62: Safety circuit 8  
Value in PointValue (107) = Alarm flag 63: Data logging memory full  
Value in PointValue (108) = Alarm flag 64: Memory check failure  
Value in PointValue (109) = Alarm flag 65: Storage memory full  
Value in PointValue (110) = Alarm flag 66: Power failure  
Value in PointValue (111) = Alarm flag 67: Unable to ramp down  
Value in PointValue (112) = Alarm flag 68: MPMC 1 failure  
Value in PointValue (113) = Alarm flag 69: MPMC 2 failure  
Value in PointValue (114) = Alarm flag 70: Calibration failure meter 1  
Value in PointValue (115) = Alarm flag 71: Calibration failure meter 2  
Value in PointValue (116) = Alarm flag 72: Calibration failure meter 3  
Value in PointValue (117) = Alarm flag 73: Calibration failure meter 4  
Value in PointValue (118) = Alarm flag 74: Intermediate level input  
Value in PointValue (119) = Alarm flag 75: RESERVED  
Value in PointValue (120) = Alarm flag 76: RESERVED  
Value in PointValue (121) = Alarm flag 77: RESERVED  
Value in PointValue (122) = Alarm flag 78: RESERVED  
Value in PointValue (123) = Alarm flag 79: RESERVED

## STATUS FLAGS:

The status flags indicate the operational state of the DanLoad 6000. When the DanLoad 6000 is in automatic, the automation system influences the operational state of the DanLoad 6000. However, status flags are updated by the DanLoad 6000 in both automatic and manual.

Bits marked '\*' are cleared on power-up/reset. Bits marked '#' are cleared by a Start Communications command. Bits marked 'a' can be cleared using the Clear Status command. Bits marked 'B' indicated statuses which prevent the automation system from displaying messages on the DanLoad 6000. All flags are cleared on a 'cold start'.

## **Reported exceptions:**

- None

## **Important note:**

The driver will stop assigning PointValues when it reaches the configured DriverNumPoints. Remaining PointValues will be filled with a value of -1.

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## Clear Status

### Description of this command:

This command allows the automation system to clear certain status flags.

A '1' in any bit indicates a request to clear the corresponding status flag on the DanLoad 6000.

Valid modes: Automatic.

### Methods used to run this command:

Analog Output

### Number of points accepted by this command:

32

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

13h (19 dec)

### Values that are sent:

Value in PointValue (0) = Status flag 0: 00hB Operating mode is manual

Value in PointValue (1) = Status flag 1: 01hB Primary alarm

Value in PointValue (2) = Status flag 2: 02h\* Passcode entry in progress

Value in PointValue (3) = Status flag 3: 03h\*#a Operation timed out

Value in PointValue (4) = Status flag 4: 04h\*#a Recipe selected

Value in PointValue (5) = Status flag 5: 05h\*#a Additives selected, i.e. additive selection complete

Value in PointValue (6) = Status flag 6: 06h\*#a Preset volume entered

Value in PointValue (7) = Status flag 7: 07h\*#a Keypad data available

Value in PointValue (8) = Status flag 8: 08ha Program code value(s) changed

Value in PointValue (9) = Status flag 9: 09h\* Transaction in progress

Value in PointValue (10) = Status flag 10: 0Ah\*B Batch in progress (doesn't necessarily imply delivery)

Value in PointValue (11) = Status flag 11: 0Bh\*a Key pressed (DanLoad 6000 v5.1 1 and above)

Value in PointValue (12) = Status flag 12: 0Cha Transaction ended

Value in PointValue (13) = Status flag 13: 0Dha Batch ended

Value in PointValue (14) = Status flag 14: 0Eh\*a Batch aborted (not started)

Value in PointValue (15) = Status flag 15: 0Fh\*a Intermediate level input alarm stopped batch (v5.50)

Value in PointValue (16) = Status flag 16: IOh RESERVED

Value in PointValue (17) = Status flag 17: 11h Batch authorized

Value in PointValue (18) = Status flag 18: 12h Transaction authorized

Value in PointValue (19) = Status flag 19: 13ha Transaction end requested ("STOP" key in auto)

Value in PointValue (20) = Status flag 20: 14h Keypad and display locked out to automation system

Value in PointValue (21) = Status flag 21: 15h Batch stopped (resumable)

Value in PointValue (22) = Status flag 22: 16ha Program mode

Value in PointValue (23) = Status flag 23: 17h\* Flowing, i.e. batch in progress and not stopped

Value in PointValue (24) = Status flag 24: 18h RESERVED

Value in PointValue (25) = Status flag 25: 19h RESERVED

Value in PointValue (26) = Status flag 26: IAh RESERVED

Value in PointValue (27) = Status flag 27: IBh RESERVED

Value in PointValue (28) = Status flag 28: ICh RESERVED

Value in PointValue (29) = Status flag 29: IDh RESERVED

Value in PointValue (30) = Status flag 30: IEh RESERVED

Value in PointValue (31) = Status flag 31: IFh RESERVED

### Important note:

- Only the status flags marked with 'a' (see below) can be cleared using the Clear Status command.

### Status flags immediately set:

- None

### Status flags immediately cleared:

- Various

### Reported exceptions:

- 12h Status not set or cannot be reset
- 15h Operating mode is manual

### FLAGS THAT CAN BE CLEARED WITH THIS COMMAND

- Status flag 3: 03h\*#a Operation timed out
- Status flag 4: 04h\*#a Recipe selected

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- Status flag 5: 05h\*#a Additives selected, i.e. additive selection complete
- Status flag 6: 06h\*#a Preset volume entered
- Status flag 7: 07h\*#a Keypad data available
- Status flag 8: 08ha Program code value(s) changed
- Status flag 11: 0Bh\*#a Key pressed (DanLoad 6000 v5.1 1 and above)
- Status flag 12: 0Cha Transaction ended
- Status flag 13: 0Dha Batch ended
- Status flag 14: 0Eh\*#a Batch aborted (not started)
- Status flag 15: 0Fh\*#a Intermediate level input alarm stopped batch (v5.50)
- Status flag 19: 13ha Transaction end requested ('STOP" key in auto)
- Status flag 22: 16ha Program mode

#### Important note:

The driver will stop assigning PointValues when it reaches the configured DriverNumPoints. Remaining PointValues will be filled with a value of -1.

## Change Operating Mode

#### Description of this command:

The Change Operating Mode command allows the automation system to change the DanLoad 6000's operating mode if the auto/manual change-over input is not configured. The Change Operating Mode command is the communications equivalent of the auto/manual change-over input.

If the DanLoad 6000's operating mode is controlled by the auto/manual change-over input an exception response is generated.

If the DanLoad 6000 is already in the desired operating mode then the command is simply acknowledged.

The operating mode does not change until the transaction has ended.

Status flag 00h (Operating mode is manual) is set or cleared subsequently.

Valid modes: Manual / Automatic.

#### Methods used to run this command:

Analog Output

#### Number of points accepted by this command:

1

#### Meaning of the DriverP0 parameter:

Device number (1-255)

#### Meaning of the DriverP1 parameter:

37h (55 dec)

#### Meaning of the DriverP2 parameter:

Operating mode (0=Auto, 1=Manual)

#### Values that are sent:

Value in PointValue (0) = Ignored. Can be any value.

#### Status flags immediately set:

- None

#### Status flags immediately cleared:

- None

#### Reported exceptions:

- 27h Operating mode cannot be changed
- 4Dh Invalid operating mode

#### Important note:

This command does not use the values assigned to the PointValue properties, which means that any value there will be ignored.

## Display Message

#### Description of this command:

The DanLoad 6000 displays 'Message text' on the bottom line of the display. Invalid characters in 'Message text' are replaced by an asterisk.

If 'Prompt field width' is zero all forty columns are used. If 'Prompt field width' is non-zero the first thirty two columns are used. If necessary, the message text is scrolled within the appropriate number of columns. One space is inserted at the end of the message for scrolling purposes.

If 'Prompt field width' is less than zero then zero is assumed. If 'Prompt field width' is greater than eight then eight is assumed.

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If 'Prompt field width' is non-zero the DanLoad 6000 prompts for 'Prompt field width' input characters starting at column thirty three. The 'CLEAR' key clears the input field and restarts input entry. The 'ENTER' key terminates input entry. If 'ENTER' is pressed when the input field is blank the keypad data available to the automation system has a value of zero.

*Valid input control ('Input control') values are:*

- 0 = Echo numeric keys on the display.
- 1 = Display an asterisk "\*" for each numeric key pressed.

If 'Prompt field width' is greater than zero the time-out specified by 'Timeout' is reset whenever a key is pressed. If 'Prompt field width' is zero a time-out occurs after the specified 'Timeout'; this allows the automation system to display a message 'for a few seconds'. If 'Timeout' is zero the automation system can terminate the operation with a Time-Out Operation command. If a time-out occurs the keypad data is not available to the automation system since the timed-out status flag is set and the keypad data available status flag is clear.

*Valid time-out ('Timeout') values are:*

- -1 = Use the configured time-out, i.e. the number of seconds specified by program code 036.
- 0 = No time-out, i.e. display/prompt until a Time-Out Operation command.
- >0 = Use the supplied time-out, i.e. the number of seconds specified in the message.

Valid modes: Automatic.

#### **Methods used to run this command:**

Analog Output

#### **Number of points accepted by this command:**

1

#### **Meaning of the DriverP0 parameter:**

Device number (1-255)

#### **Meaning of the DriverP1 parameter:**

1Ch (28 dec)

#### **Meaning of the DriverP2 parameter:**

Prompt field width (0-8)

#### **Meaning of the DriverP3 parameter:**

Input control (0-1)

#### **Meaning of the DriverP4 parameter:**

Timeout

#### **Meaning of the DriverP5 parameter:**

Not used

#### **Meaning of the DriverP6 parameter:**

Message text (up to 128 chars)

#### **Values that are sent:**

Value in PointValue (0) = Ignored. Can be any value.

#### **Status flags immediately set:**

- 14h Keypad and display locked out

#### **Status flags immediately cleared:**

- 03h Operation timed out
- 07h Keypad data available

#### **Reported exceptions:**

- 01 h Passcode entry in progress
- 08h Batch in progress
- 0Ah Primary alarm is active
- 15h Operating mode is manual (low priority, may not be seen!)
- 24h Keypad and display locked out

#### **Important note:**

This command does not use the values assigned to the PointValue properties, which means that any value there will be ignored.

## Clear Display

#### **Description of this command:**

This command clears the DanLoad 6000's multi-line display. The DanLoad 6000 displays the date and time in the upper right hand corner and 'Please wait' on the bottom line.

This command can be used to erase the recipe menu after a Prompt Recipe command, the additive menu after a Prompt Additive command or the loading screen after an Authorize Transaction command, a Prompt Preset Volume command or an Authorized Batch command.

Valid modes: Automatic.

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**Methods used to run this command:**

Analog Output

**Number of points accepted by this command:**

1

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

38h (56 dec)

**Values that are sent:**

Value in PointValue (0) = Ignored. Can be any value.

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 01 h Passcode entry in progress
- 15h Operating mode is manual (low priority, may not be seen!)
- 24h Keypad and display locked out

**Important note:**

This command does not use the values assigned to the PointValue properties, which means that any value there will be ignored.

## Read Input

**Description of this command:**

*Valid I/O point types are:*

- 0 = Meter input.
- 1 = RTD input.
- 2 = Current loop input.
- 3 = Discrete input. The automation system should specify the actual discrete input (rather than the 'inverted discrete input', #51 and above) for the I/O point number.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

1

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

2Bh (43 dec)

**Meaning of the DriverP2 parameter:**

I/O Point type (0-3)

**Meaning of the DriverP3 parameter:**

I/O Point number

**Values that are returned:**

Value in PointValue (0) = Discrete, meter, RTD or current loop value

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 4Ah Invalid I/O point type
- 4Bh Invalid I/O point number

## Write Output

**Description of this command:**

*Valid I/O point types are:*

- 4 = Discrete input.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Output

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## Number of points accepted by this command:

1

## Meaning of the DriverP0 parameter:

Device number (1-255)

## Meaning of the DriverP1 parameter:

2Ch (44 dec)

## Meaning of the DriverP2 parameter:

I/O Point type (0-3)

## Meaning of the DriverP3 parameter:

I/O Point number

## Values that are sent:

Value in PointValue (0) = Discrete output value

## Status flags immediately set:

- None

## Status flags immediately cleared:

- None

## Reported exceptions:

- 4Ah Invalid I/O point type
- 4Bh Invalid I/O point number
- 4Ch Invalid output value

## Reset Primary Alarms

### Description of this command:

This command allows multiple active primary alarms to be reset. If the chronologically oldest active primary alarm is reset this command has the same effect as a primary alarm reset via the alarm reset screen or the alarm reset switch (program code 344). NOTE: Before you execute this command, you must set to 1 those PointValues that correspond to the alarm flags to be reset. Valid modes: Automatic.

### Methods used to run this command:

Analog Output

### Number of points accepted by this command:

80

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

14h (20 dec)

### Values that are sent:

- Value in PointValue (0) = Alarm flag 0: Primary display failure
- Value in PointValue (1) = Alarm flag 1: Secondary display failure
- Value in PointValue (2) = Alarm flag 2: Comms failure channel A
- Value in PointValue (3) = Alarm flag 3: Comms failure channel B
- Value in PointValue (4) = Alarm flag 4: Unable to maintain blend
- Value in PointValue (5) = Alarm flag 5: Flow rate too low meter 1
- Value in PointValue (6) = Alarm flag 6: Flow rate too low meter 2
- Value in PointValue (7) = Alarm flag 7: Flow rate too low meter 3
- Value in PointValue (8) = Alarm flag 8: Flow rate too low meter 4
- Value in PointValue (9) = Alarm flag 9: Flow rate too high meter 1
- Value in PointValue (10) = Alarm flag 10: Flow rate too high meter 2
- Value in PointValue (11) = Alarm flag 11: Flow rate too high meter 3
- Value in PointValue (12) = Alarm flag 12: Flow rate too high meter 4
- Value in PointValue (13) = Alarm flag 13: Valve closed early meter 1
- Value in PointValue (14) = Alarm flag 14: Valve closed early meter 2
- Value in PointValue (15) = Alarm flag 15: Valve closed early meter 3
- Value in PointValue (16) = Alarm flag 16: Valve closed early meter 4
- Value in PointValue (17) = Alarm flag 17: Time-out - no flow detected meter 1
- Value in PointValue (18) = Alarm flag 18: Time-out - no flow detected meter 2
- Value in PointValue (19) = Alarm flag 19: Time-out - no flow detected meter 3
- Value in PointValue (20) = Alarm flag 20: Time-out - no flow detected meter 4
- Value in PointValue (21) = Alarm flag 21: Unauthorized flow exceeds limit meter 1
- Value in PointValue (22) = Alarm flag 22: Unauthorized flow exceeds limit meter 2
- Value in PointValue (23) = Alarm flag 23: Unauthorized flow exceeds limit meter 3
- Value in PointValue (24) = Alarm flag 24: Unauthorized flow exceeds limit meter 4

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Value in PointValue (25) = Alarm flag 25: Pulse security error meter 1  
Value in PointValue (26) = Alarm flag 26: Pulse security error meter 2  
Value in PointValue (27) = Alarm flag 27: Pulse security error meter 3  
Value in PointValue (28) = Alarm flag 28: Pulse security error meter 4  
Value in PointValue (29) = Alarm flag 29: Temperature failure meter 1  
Value in PointValue (30) = Alarm flag 30: Temperature failure meter 2  
Value in PointValue (31) = Alarm flag 31: Temperature failure meter 3  
Value in PointValue (32) = Alarm flag 32: Temperature failure meter 4  
Value in PointValue (33) = Alarm flag 33: Pressure failure meter 1  
Value in PointValue (34) = Alarm flag 34: Pressure failure meter 2  
Value in PointValue (35) = Alarm flag 35: Pressure failure meter 3  
Value in PointValue (36) = Alarm flag 36: Pressure failure meter 4  
Value in PointValue (37) = Alarm flag 37: Unable to close valve meter 1  
Value in PointValue (38) = Alarm flag 38: Unable to close valve meter 2  
Value in PointValue (39) = Alarm flag 39: Unable to close valve meter 3  
Value in PointValue (40) = Alarm flag 40: Unable to close valve meter 4  
Value in PointValue (41) = Alarm flag 41: Density failure component 1  
Value in PointValue (42) = Alarm flag 42: Density failure component 2  
Value in PointValue (43) = Alarm flag 43: Density failure component 3  
Value in PointValue (44) = Alarm flag 44: Density failure component 4  
Value in PointValue (45) = Alarm flag 45: Component 1 block valve not closed  
Value in PointValue (46) = Alarm flag 46: Component 2 block valve not closed  
Value in PointValue (47) = Alarm flag 47: Component 3 block valve not closed  
Value in PointValue (48) = Alarm flag 48: Component 4 block valve not closed  
Value in PointValue (49) = Alarm flag 49: Additive 1 failure  
Value in PointValue (50) = Alarm flag 50: Additive 2 failure  
Value in PointValue (51) = Alarm flag 51: Additive 3 failure  
Value in PointValue (52) = Alarm flag 52: Additive 4 failure  
Value in PointValue (53) = Alarm flag 53: Additive 5 failure  
Value in PointValue (54) = Alarm flag 54: Additive 6 failure  
Value in PointValue (55) = Alarm flag 55: Safety circuit 1  
Value in PointValue (56) = Alarm flag 56: Safety circuit 2  
Value in PointValue (57) = Alarm flag 57: Safety circuit 3  
Value in PointValue (58) = Alarm flag 58: Safety circuit 4  
Value in PointValue (59) = Alarm flag 49: Safety circuit 5  
Value in PointValue (60) = Alarm flag 60: Safety circuit 6  
Value in PointValue (61) = Alarm flag 61: Safety circuit 7  
Value in PointValue (62) = Alarm flag 62: Safety circuit 8  
Value in PointValue (63) = Alarm flag 63: Data logging memory full  
Value in PointValue (64) = Alarm flag 64: Memory check failure  
Value in PointValue (65) = Alarm flag 65: Storage memory full  
Value in PointValue (66) = Alarm flag 66: Power failure  
Value in PointValue (67) = Alarm flag 67: Unable to ramp down  
Value in PointValue (68) = Alarm flag 68: MPMC 1 failure  
Value in PointValue (69) = Alarm flag 69: MPMC 2 failure  
Value in PointValue (70) = Alarm flag 70: Calibration failure meter 1  
Value in PointValue (71) = Alarm flag 71: Calibration failure meter 2  
Value in PointValue (72) = Alarm flag 72: Calibration failure meter 3  
Value in PointValue (73) = Alarm flag 73: Calibration failure meter 4  
Value in PointValue (74) = Alarm flag 74: Intermediate level input  
Value in PointValue (75) = Alarm flag 75: RESERVED  
Value in PointValue (76) = Alarm flag 76: RESERVED  
Value in PointValue (77) = Alarm flag 77: RESERVED  
Value in PointValue (78) = Alarm flag 78: RESERVED  
Value in PointValue (79) = Alarm flag 79: RESERVED

#### Status flags immediately set:

- None

#### Status flags immediately cleared:

- None

#### Reported exceptions:

- 01 h Passcode entry in progress
- 15h Operating mode is manual (low priority, may not be seen!)

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## Prompt Preset Volume

### Description of this command:

(The loading display is already displayed).

The DanLoad 6000 prompts the operator to enter a preset volume. If the suggested preset volume is greater than zero, the DanLoad 6000 pre-types the suggested preset volume and the operator need only press ENTER, or can press CLEAR and enter another volume.

If the override maximum preset volume is greater than zero the DanLoad 6000 ensures that the preset volume is less than or equal to the minimum of the configured maximum preset volume and the override maximum preset volume included in the Prompt Preset Volume command.

The configured maximum preset volume is not modified by this command.

The DanLoad 6000 sets a flag to indicate that the preset volume is available or that a time-out occurred, displays Please wait and waits for a command.

The Prompt Preset Volume command does not clear the batch ended status flag. However, the Authorize Batch command does clear the batch ended status flag. Thus, depending on the design of the automation system, it may not be necessary for the automation system to clear the batch ended status flag with the Clear Status (13h) command after obtaining batch data with the Batch Data by Component (10h) command.

Valid modes: Automatic.

### Methods used to run this command:

Analog Output

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

08h (8 dec)

### Meaning of the DriverP2 parameter:

Suggested preset volume

### Meaning of the DriverP3 parameter:

Maximum preset volume

### Meaning of the DriverP4 parameter:

Time-out seconds (0=No time-out, <0=Use configured time-out)

### Values that are sent:

Value in PointValue (0) = Ignored. Can be any value.

### Status flags immediately set:

- 14h Keypad and display locked out

### Status flags immediately cleared:

- 03h Operation timed out

- 06h Preset Volume entered

### Reported exceptions:

- 01h Passcode entry in progress

- 08h Batch in progress

- 0Ah Primary alarm active

- 15h Operating mode is manual (low priority, may not be seen!)

- 22h No transaction authorized

- 24h Keypad and display locked out

- 4Fh Invalid preset volume

## Request Preset Volume

### Description of this command:

The DanLoad 6000 responds with volume entered by the operator in response to the Prompt Preset Volume command.

The automation system can perform further validation on the preset volume entered by the operator.

A preset volume is set in the DanLoad 6000 using the Authorize Batch command.

Valid modes: Automatic.

### Methods used to run this command:

Analog Input

### Number of points accepted by this command:

1

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**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

09h (9 dec)

**Values that are returned:**

Value in PointValue (0) = Preset volume

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 0Ah Primary alarm active
- 15h Operating mode is manual (low priority, may not be seen!)
- 16h No preset volume entered

## Time-Out Operation

**Description of this command:**

If the DanLoad 6000 is prompting for a recipe, prompting for additives, prompting for a preset volume, prompting for keypad input, displaying a message or waiting for the operator to start or abort a batch the operation is timed out.

Status flag 03h (Operation timed out) will be set subsequently.

The DanLoad 6000 displays Please wait and waits for a further command from the automation system.

Valid modes: Automatic.

**Methods used to run this command:**

Analog Output

**Number of points accepted by this command:**

1

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

05h (5 dec)

**Values that are sent:**

Value in PointValue (0) = Ignored. Can be any value.

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 01h Passcode entry in progress
- 08h Batch in progress
- 15h Operating mode is manual (low priority, may not be seen!)

## Meter Totalizers

**Description of this command:**

In a blending configuration, it is not always possible to identify which component generates unauthorized flow. More than one component may flow through a meter. The DanLoad 6000 maintains running meter totalizers (which include unauthorized flow) and running component totalizers (which exclude unauthorized flow).

Typically, the Request Meter Totalizers command would be used at the end of each shift or business day to read all meters. Thus, total meter throughput for the period can be determined and reconciled.

See the Manual of Petroleum Measurement Standards, Chapter 12, Calculation of Petroleum Quantities. When a load ticket is required, the loaded volume should be calculated as the truncated stop reading minus the truncated start reading from a non-resettable totalizer. Show meter readings from the non-resettable readout, and truncate (that is, disregard) all values less than a whole barrel or gallon.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Input

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**Number of points accepted by this command:**

$1+2*\text{Max. configured number of meters}$

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

15h (21 dec)

**Values that are returned:**

Value in PointValue (0) = Configured number of meters

- for  $i=0$  to Configured number of meters-1

Value in PointValue ( $1+2*i$ ) = Gross totalizer rolls for meter  $i$  (999999999 to 0)

Value in PointValue ( $2+2*i$ ) = Net volume or mass/weight totalizer rolls for meter  $i$  (999999999 to 0)

- next  $i$

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- None

**Important note:**

The driver will stop assigning PointValues when it reaches the configured DriverNumPoints. Remaining PointValues will be filled with a value of -1.

## Component Totalizers

**Description of this command:**

In a blending configuration, it is not always possible to identify which component generates unauthorized flow. More than one component may flow through a meter. The DanLoad 6000 maintains running meter totalizers (which include unauthorized flow) and running component totalizers (which exclude unauthorized flow).

See the Manual of Petroleum Measurement Standards, Chapter 12, Calculation of Petroleum Quantities. When a load ticket is required, the loaded volume should be calculated as the truncated stop reading minus the truncated start reading from a non-resettable totalizer. Show meter readings from the non-resettable readout, and truncate (that is, disregard) all values less than a whole barrel or gallon.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

$1+2*\text{Max. configured number of components}$

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

16h (22 dec)

**Values that are returned:**

Value in PointValue (0) = Configured number of components

- for  $i=0$  to Configured number of components-1

Value in PointValue ( $1+2*i$ ) = Gross totalizer rolls for component  $i$  (999999999 to 0)

Value in PointValue ( $2+2*i$ ) = Net volume or mass/weight totalizer rolls for component  $i$  (999999999 to 0)

- next  $i$

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- None

**Important note:**

The driver will stop assigning PointValues when it reaches the configured DriverNumPoints. Remaining PointValues will be filled with a value of -1.

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## Request Keypad Data

### Description of this command:

This command is used to retrieve input requested via the Display Message command. When keypad input is terminated the DanLoad 6000 sets a flag indicating that keypad data is available. The keypad data is a binary representation of the number entered by the operator at the DanLoad 6000.

Valid modes: Automatic.

### Methods used to run this command:

Analog Input

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

1Dh (29 dec)

### Values that are returned:

Value in PointValue (0) = Keypad data

### Status flags immediately set:

- None

### Status flags immediately cleared:

- None

### Reported exceptions:

- 08h Batch in progress

- 0Ah Primary alarm active

- 0Eh No keypad data available

- 15h Operating mode is manual (low priority, may not be seen!)

## Reset Unit

### Description of this command:

The DanLoad 6000 responds to the automation system and then resets (similar to power up).

The DanLoad 6000's CPU-1 issues a reset instruction which resets both CPU-1 and CPU-2.

Valid modes: Manual / Automatic.

### Methods used to run this command:

Analog Output

### Number of points accepted by this command:

1

### Meaning of the DriverP0 parameter:

Device number (1-255)

### Meaning of the DriverP1 parameter:

30h (48 dec)

### Values that are sent:

Value in PointValue (0) = Ignored. Can be any value.

### Status flags immediately set:

- None

### Status flags immediately cleared:

- None

### Reported exceptions:

- 09h Transaction in progress

### Important note:

Previously documented as being valid only in the automatic operating mode and giving an exception in the manual operating mode. Refer to standard DanLoad 6000 fault 222.

## Last Key Pressed

### Description of this command:

The DanLoad 6000 responds with the key code of the keypad key most recently pressed.

In DanLoad 6000 v5.11 and above, the Key Pressed (0Bh) status flag (in the response to the Request Status (12h) and Enhanced Request Status (3Ch) commands) indicates if a key code is available. The Key Pressed status flag can be cleared by the automation system using the Clear Status (13h) command if a new key code is required.

Valid modes: Manual / Automatic.

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**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

1

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

31h (49 dec)

**Values that are returned:**

Value in PointValue (0) = Keycode

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 1Ah No key pressed, i.e. no key code available

## Request Stored Transaction

**Description of this command:**

This command is used to request a transaction record from the (transaction storage) transaction file. The format of the transaction record is configurable.

Valid transaction sequence numbers are 0 through 9999. In practice, fewer than 10,000 transactions may actually be stored.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

Number of transaction record values (1-250)

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

39h (57 dec)

**Meaning of the DriverP2 parameter:**

Transaction sequence number (0-9999)

**Values that are returned:**

- for i=0 to Number of transaction record values-1

Value in PointValue (i) = Transaction record values(i) (0-255)

- next i

**Status flags immediately set:**

- None

**Status flags immediately cleared:**

- None

**Reported exceptions:**

- 1Dh Transaction not on file (transaction storage)

## Request Stored Batch

**Description of this command:**

This command is used to request a batch record from the (transaction storage) batch file. The format of the batch record is configurable.

Valid batch sequence numbers are 0 through 9999. In practice, fewer than 10,000 batches may actually be stored.

Valid modes: Manual / Automatic.

**Methods used to run this command:**

Analog Input

**Number of points accepted by this command:**

Number of batch record values (1-250)

**Meaning of the DriverP0 parameter:**

Device number (1-255)

**Meaning of the DriverP1 parameter:**

3Ah (58 dec)

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## Meaning of the DriverP2 parameter:

Batch sequence number (0-9999)

## Values that are returned:

- for i=0 to Number of batch record values-1

Value in PointValue (i) = Transaction record values(i) (0-255)

- next i

## Status flags immediately set:

- None

## Status flags immediately cleared:

- None

## Reported exceptions:

- 1Eh Batch not on file (transaction storage)

## Error messages

---

The following list shows the possible error messages that can be returned by the driver during a failed communication in the 'Status' property.

[1005] DRIVER (Internal): Invalid driver stage  
[1300] PROTOCOL (Timeout): No answer  
[1313] PROTOCOL (Timeout): No answer from meter after retrying with a Start Communications message  
[1408] PROTOCOL (Format): Invalid amount of data bytes received  
[2232] CONFIG (NumValues): Too many values (max=7)  
[2295] CONFIG (NumValues): Invalid number of values (must be 32)  
[2296] CONFIG (NumValues): Invalid number of values (must be 80)  
[3022] CONFIG (P0): Invalid device address (1-255)  
[3502] CONFIG (P1): Command not implemented  
[3508] CONFIG (P1): Invalid command  
[3592] CONFIG (P1): Invalid command received in reply  
[4144] CONFIG (P2): Invalid meter number (1-4)  
[4145] CONFIG (P2): Invalid recipe number (1-30)  
[4147] CONFIG (P2): Invalid swing-arm side (0-2)  
[4148] CONFIG (P2): Invalid operating mode (0-1)  
[4149] CONFIG (P2): Invalid prompt field width (0-8)  
[4150] CONFIG (P2): Invalid point type (0-3)  
[4151] CONFIG (P2): Invalid point type (4 only)  
[4152] CONFIG (P2): Invalid transaction sequence number (0-9999)  
[4153] CONFIG (P2): Invalid preset volume (must be >0)  
[4154] CONFIG (P2): Invalid batch sequence number (0-9999)  
[4594] CONFIG (P3): Invalid additive selection method (0-1)  
[4595] CONFIG (P3): Invalid number of components (0-50)  
[4596] CONFIG (P3): Invalid number of components (0-30)  
[4597] CONFIG (P3): Invalid input control (0-1)  
[4598] CONFIG (P3): Invalid maximum preset volume (must be >0)  
[5043] CONFIG (P4): Invalid value for this parameter  
[5517] CONFIG (P5): Invalid swing-arm side (0-2)  
[6042] CONFIG (P6): Invalid number of data prompts (0-5)  
[6043] CONFIG (P6): Recipe name cannot be empty  
[8404] CONFIG (Remote): 00h Invalid command code  
[8405] CONFIG (Remote): 01h Passcode entry in progress  
[8406] CONFIG (Remote): 02h No transaction ended  
[8407] CONFIG (Remote): 03h Response's data field too long  
[8408] CONFIG (Remote): 04h Program code value is Weights and Measures  
[8409] CONFIG (Remote): 05h RESERVED  
[8410] CONFIG (Remote): 06h No batch in progress  
[8411] CONFIG (Remote): 07h No transaction in progress  
[8412] CONFIG (Remote): 08h Batch in progress  
[8413] CONFIG (Remote): 09h Transaction in progress  
[8414] CONFIG (Remote): 0Ah Primary alarm active  
[8415] CONFIG (Remote): 0Bh Batch authorized  
[8416] CONFIG (Remote): 0Ch Transaction authorized

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[8417] CONFIG (Remote): 0Dh RESERVED  
[8418] CONFIG (Remote): 0Eh No keypad data available  
[8419] CONFIG (Remote): 0Fh Component not available  
[8420] CONFIG (Remote): 10h Additive not available  
[8421] CONFIG (Remote): 11h Program code value is read only  
[8422] CONFIG (Remote): 12h Status not set or cannot be reset  
[8423] CONFIG (Remote): 13h No additives configured  
[8424] CONFIG (Remote): 14h No batch authorized  
[8425] CONFIG (Remote): 15h Operating mode is manual  
[8426] CONFIG (Remote): 16h No preset volume entered  
[8427] CONFIG (Remote): 17h No recipe selected  
[8428] CONFIG (Remote): 18h No additive selection made  
[8429] CONFIG (Remote): 19h Data items not entered  
[8430] CONFIG (Remote): 1Ah No key pressed  
[8431] CONFIG (Remote): 1Bh Diagnostic not started  
[8432] CONFIG (Remote): 1Ch Diagnostic running  
[8433] CONFIG (Remote): 1Dh Transaction not on file (transaction storage)  
[8434] CONFIG (Remote): 1Eh Batch not on file (transaction storage)  
[8435] CONFIG (Remote): 1Fh RESERVED  
[8436] CONFIG (Remote): 20h Number of recipes < 2 (Not DanLoad 6000 v5.00 and above)  
[8437] CONFIG (Remote): 21h RESERVED  
[8438] CONFIG (Remote): 22h No transaction authorized  
[8439] CONFIG (Remote): 23h RESERVED  
[8440] CONFIG (Remote): 24h Keypad and display locked out  
[8441] CONFIG (Remote): 25h No batch stopped  
[8442] CONFIG (Remote): 26h No batch ended  
[8443] CONFIG (Remote): 27h Operating mode cannot be changed  
[8444] CONFIG (Remote): 28h RESERVED  
[8445] CONFIG (Remote): 29h RESERVED  
[8446] CONFIG (Remote): 2Ah RESERVED  
[8447] CONFIG (Remote): 2Bh RESERVED  
[8448] CONFIG (Remote): 2Ch RESERVED  
[8449] CONFIG (Remote): 2Dh RESERVED  
[8450] CONFIG (Remote): 2Eh RESERVED  
[8451] CONFIG (Remote): 2Fh RESERVED  
[8452] CONFIG (Remote): 30h RESERVED  
[8453] CONFIG (Remote): 31h RESERVED  
[8454] CONFIG (Remote): 32h RESERVED  
[8455] CONFIG (Remote): 33h RESERVED  
[8456] CONFIG (Remote): 34h RESERVED  
[8457] CONFIG (Remote): 35h RESERVED  
[8458] CONFIG (Remote): 36h RESERVED  
[8459] CONFIG (Remote): 37h RESERVED  
[8460] CONFIG (Remote): 38h RESERVED  
[8461] CONFIG (Remote): 39h RESERVED  
[8462] CONFIG (Remote): 3Ah RESERVED  
[8463] CONFIG (Remote): 3Bh RESERVED  
[8464] CONFIG (Remote): 3Ch RESERVED  
[8465] CONFIG (Remote): 3Dh RESERVED  
[8466] CONFIG (Remote): 3Eh RESERVED  
[8467] CONFIG (Remote): 3Fh RESERVED  
[8468] CONFIG (Remote): 40h Invalid recipe number  
[8469] CONFIG (Remote): 41h Invalid meter number  
[8470] CONFIG (Remote): 42h Invalid component number  
[8471] CONFIG (Remote): 43h Invalid transaction sequence number  
[8472] CONFIG (Remote): 44h Invalid program code  
[8473] CONFIG (Remote): 45h Invalid program code value  
[8474] CONFIG (Remote): 46h Invalid CPU number  
[8475] CONFIG (Remote): 47h Invalid number of components  
[8476] CONFIG (Remote): 48h Invalid number of data items  
[8477] CONFIG (Remote): 49h Invalid swing-arm side  
[8478] CONFIG (Remote): 4Ah Invalid I/O point type

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[8479] CONFIG (Remote): 4Bh Invalid I/O point number  
[8480] CONFIG (Remote): 4Ch Invalid output value  
[8481] CONFIG (Remote): 4Dh Invalid operating mode  
[8482] CONFIG (Remote): 4Eh Invalid additive selection method  
[8483] CONFIG (Remote): 4Fh Invalid preset volume  
[8484] CONFIG (Remote): 50h Invalid date  
[8485] CONFIG (Remote): 51h Invalid time  
[8486] CONFIG (Remote): 52h Invalid data code  
[8487] CONFIG (Remote): 53h Invalid override maximum preset volume  
[8488] CONFIG (Remote): 54h Invalid board type  
[8489] CONFIG (Remote): 55h Invalid bit #

## Supported devices

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This driver can communicate with these devices, but is not necessarily limited to this list:

EMERSON DANIEL DANLOAD 6000 Electronic Presets

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